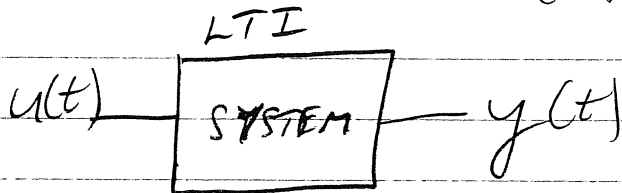


FRI

FREQUENCY RESPONSE REVIEW

CAN DEFINE A FREQUENCY RESPONSE
FOR A LINEAR TIME-INVARIANT SYSTEM
(LTI)



LINEAR IF $u_1(t)$ RESULTS IN $y_1(t)$

$u_2(t)$ RESULTS IN $y_2(t)$

THEN LINEAR IF AND ONLY IF

$u_1(t) + u_2(t)$ RESULTS IN $y_1(t) + y_2(t)$

FOR ANY $u_1(t), u_2(t)$

TIME INVARIANT

TIME INVARIANT IF & ONLY IF

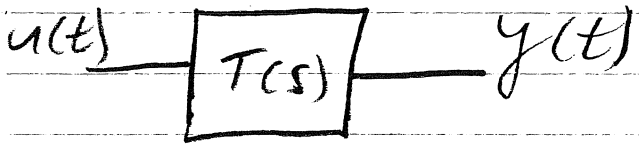
IF $u_1(t)$ RESULTS IN $y_1(t)$

THEN $u_1(t - \tau)$ RESULTS IN $y_1(t - \tau)$

FOR ANY $u_1(t) \& \tau$

FREQUENCY RESPONSE

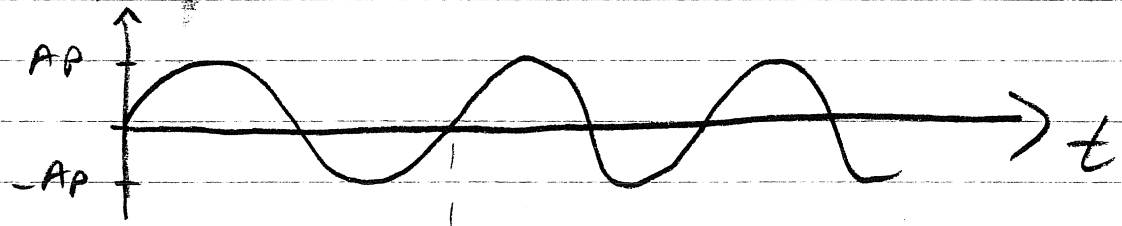
LET LTI SYSTEM HAVE TRANSFER FUNCTION $T(s)$



FREQUENCY RESPONSE IS GIVEN BY LETTING $s = j\omega$ WHERE " ω " IS ANGULAR FREQUENCY IN RAD/S

$\omega = 2\pi f$ WHERE f IS IN $\frac{\text{CYCLES}}{S}$ OR HZ

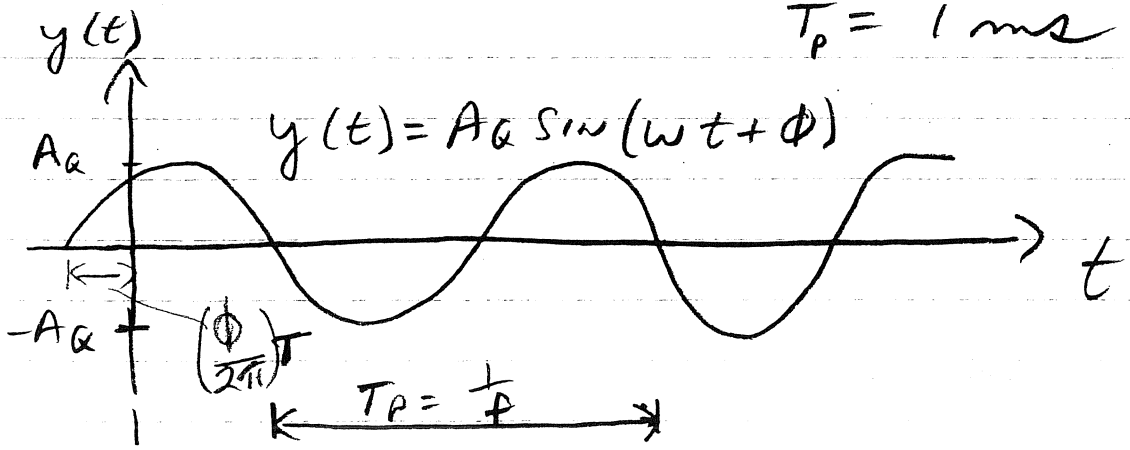
$u(t) = A_p \sin(\omega t) = A_p \sin(2\pi f t)$



$T_p = \frac{1}{f} = \frac{2\pi}{\omega}$

FOR $\omega = 6.28 \times 10^3$ RAD/S
 $f = \frac{\omega}{2\pi} = 1 \text{ KHz}$

$T_p = 1 \text{ ms}$



FOR LTI

(FR3)

IF INPUT IS SINUSOIDAL WITH FREQ f
THEN OUTPUT IS ALSO SINUSOIDAL
WITH FREQ f BUT DIFFERENT AMPLITUDE + PHASE

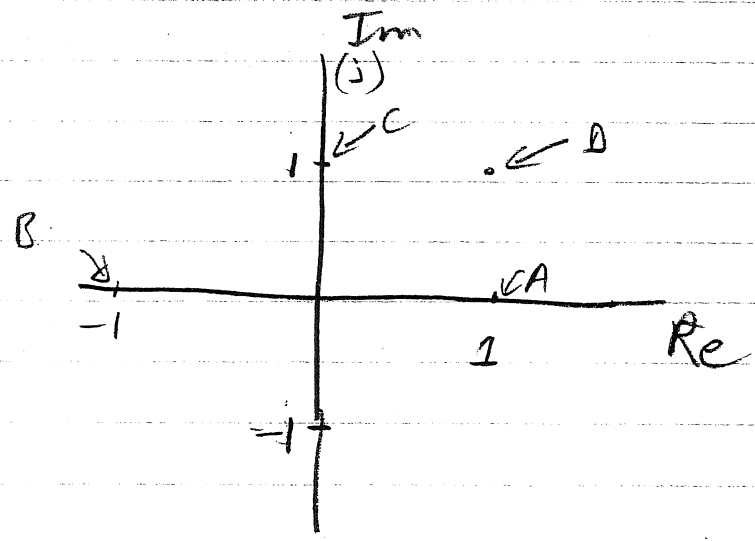
$$\frac{A_Q}{A_P} = |T(j\omega)| \quad \begin{array}{l} \text{MAGNITUDE} \\ \text{RESPONSE} \end{array}$$

$$\phi = \angle T(j\omega)$$

$T(j\omega)$ IS A COMPLEX NUMBER WHERE
THE $|T(j\omega)|$ IS MAGNITUDE RESPONSE

$\angle T(j\omega)$ IS PHASE RESPONSE

COMPLEX NUMBERS



$A = 1 \quad |A| = 1 \quad \angle A = 0^\circ$

$B = -1 \quad |B| = 1 \quad \angle B = 180^\circ$

$C = j \quad |C| = 1 \quad \angle C = 90^\circ$

$D = 1 + j \quad |D| = \sqrt{2} \quad \angle D = 45^\circ$

If $Z = a + jb$

Z COMPLEX
a, b REAL

$|Z| = (a^2 + b^2)^{\frac{1}{2}}$

$\angle Z = \tan^{-1}\left(\frac{b}{a}\right) \quad \text{IF } a > 0$

$\angle Z = \tan^{-1}\left(\frac{b}{a}\right) + \pi \quad \text{IF } a < 0$

RATIO OF COMPLEX NUMBERS

$$z = \frac{z_1}{z_2} = \frac{a_1 + jb_1}{a_2 + jb_2} = \frac{|z_1| e^{j\angle z_1}}{|z_2| e^{j\angle z_2}}$$

$$|z| = \frac{|z_1|}{|z_2|} = \left(\frac{a_1^2 + b_1^2}{a_2^2 + b_2^2} \right)^{\frac{1}{2}}$$

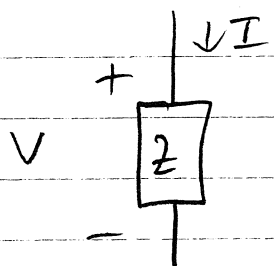
$$\angle z = \angle z_1 - \angle z_2$$

$$= \tan^{-1} \left(\frac{b_1}{a_1} \right) - \tan^{-1} \left(\frac{b_2}{a_2} \right) \quad \text{if } a_1 > 0$$

$$a_2 > 0$$

FRS

OHM'S LAW (IMPEDANCE)



$$I = \frac{V}{Z}$$

RESISTOR OF SIZE R $\Rightarrow Z = R$

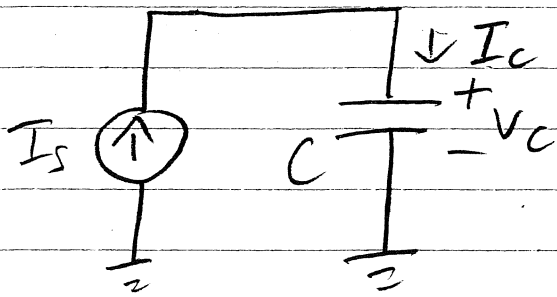
CAPACITOR OF SIZE C $\Rightarrow Z = \frac{1}{sC}$

INDUCTOR OF SIZE L $\Rightarrow Z = sL$

"s" IS LAPLACE TRANSFORM VARIABLE

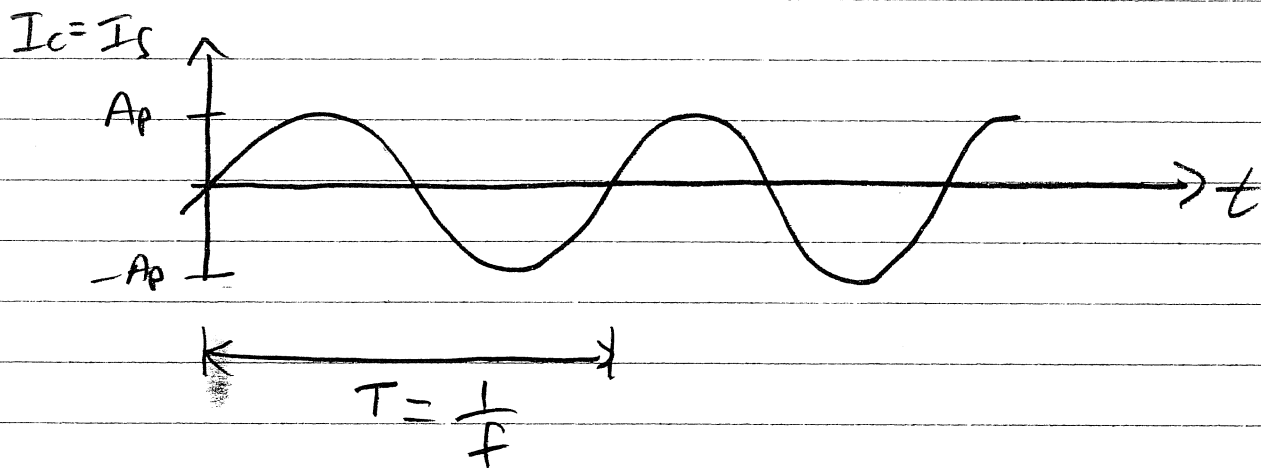
↓ WE LET $s = j\omega$ TO EVALUATE
WHAT HAPPENS AT FREQUENCY ω
(OMEGA)

WHY IS THERE THE COMPLEX
VARIABLE "j" ??

CAPACITOR

$$I_c = I_s$$

$$I_s = A_p \sin(\omega t) = A_p \sin(2\pi f t)$$



EXAMPLE

$$A_p = 1 \text{ mA}$$

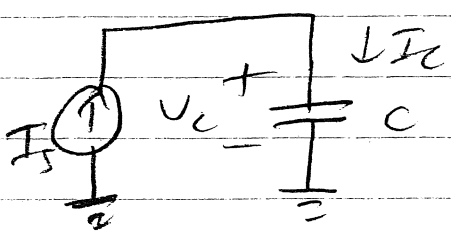
$$\omega = 6.28 \times 10^3 \text{ RAD/S}$$

$$f = \frac{\omega}{2\pi} = 1 \text{ KHz}$$

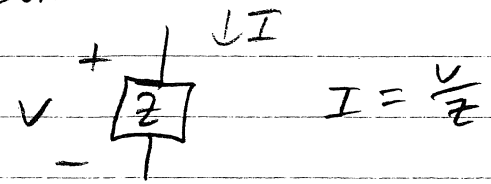
$$T = 1 \text{ ms}$$

IT TURNS OUT THAT VOLTAGE V_c IS 90° OUT OF PHASE WITH I_c

HENCE THE NEED FOR "j"



RECALL



IN FREQ DOMAIN, TRANSFER FUNCTION CAN BE FOUND

$$T(s) \equiv \frac{V_c(s)}{I_c(s)} \Rightarrow I_c(s) = \frac{V_c(s)}{\left(\frac{1}{sC}\right)}$$

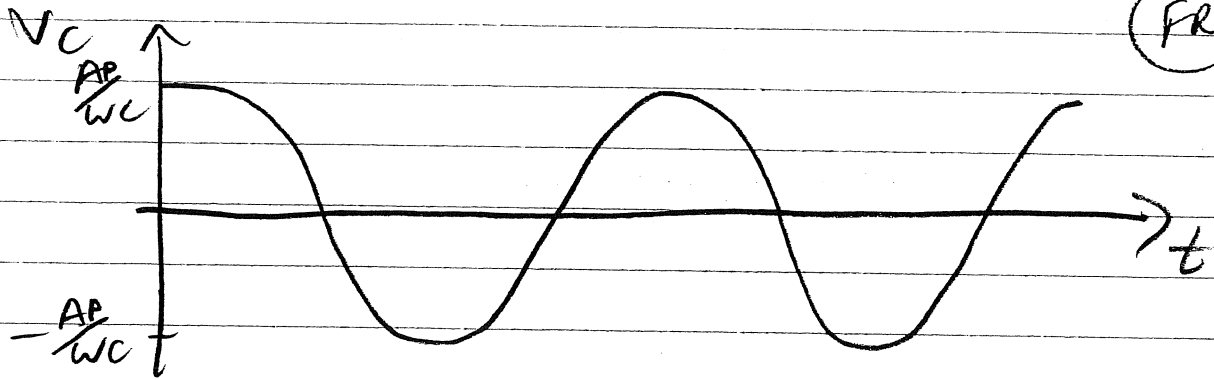
$$T(s) = \frac{V_c(s)}{I_c(s)} = \frac{1}{sC}$$

MAGNITUDE RESPONSE $|T(j\omega)| = \left| \frac{1}{j\omega C} \right| = \underline{\underline{\frac{1}{\omega C}}}$

PHASE RESPONSE $\angle T(j\omega) = \angle \left(\frac{1}{j\omega C} \right)$

$$\begin{aligned} \angle T(j\omega) &= \angle(1) - \angle(j\omega C) \\ &= 0^\circ - 90^\circ = \underline{\underline{-90^\circ}} \end{aligned}$$

FR8



$$I_F \quad C = 1 \mu F$$

$$\frac{A_P}{\omega C} = \frac{1 \text{ mA}}{(6.28 \times 10^3) (1 \mu F)} = 0.159 \text{ V}$$

TRANSFER-FUNCTION OF LTI

- RESTRICT OURSELVES TO

- REAL-VALUED IMPULSE RESPONSE
- CIRCUITS WITH LUMPED ELEMENTS
 - RESISTORS, CAPACITORS, INDUCTORS,
 - INDEPENDENT + DEPENDENT VOLTAGE
 - + CURRENT SOURCES

$$T(s) = \frac{a_0 + a_1 s + a_2 s^2 + \dots + a_m s^m}{1 + b_1 s + b_2 s^2 + \dots + b_n s^n} \quad (1)$$

OR

$$T(s) = \left(\frac{a_m}{b_n} \right) \frac{(s+z_1)(s+z_2) \dots (s+z_m)}{(s+w_1)(s+w_2) \dots (s+w_n)}$$

FOR STABILITY $n \geq m$

- ① POLYNOMIAL FORM
- ② ROOT FORM SHOWS ZEROS $-z_i$
POLES $-w_i$

IN GENERAL, z_i & w_i CAN BE COMPLEX VALUES + OCCUR IN COMPLEX CONJUGATE PAIRS

HOWEVER, FOR THIS FREQ ANALYSIS SECTION, ALL z_i + w_i REAL VALUED

FR10

IN OTHER WORDS, ALL POLES & ZEROS
WILL BE ON THE REAL-AXIS

ALSO FOR A STABLE SYSTEM, ALL POLES
WILL BE IN NEGATIVE HALF PLANE
(AND HENCE ON NEGATIVE REAL-AXIS HERE)

ZEROS WHERE $T(s) = 0$

ZERO AT $s = z_i \Rightarrow T(z_i) = 0$

POLES WHERE $T(s) \rightarrow \infty$

POLE AT $s = w_i \Rightarrow T(w_i) \rightarrow \infty$

EX $T(s) = \frac{1}{s+2}$ NO ZEROS
POLE $w_1 = -2$

EX $T(s) = \frac{s}{s+3}$ ZERO $z_1 = 0$
POLE $w_1 = -3$

$T(s) = \frac{s(s-2)}{(s+1)(s+3)}$ ZEROS: $z_1 = 0$ $z_2 = 2$
POLES: $p_1 = -1$ $p_2 = -3$

$$T(s) = \left(\frac{a_m}{b_n} \right) \frac{(s+z_1)(s+z_2) \dots (s+z_m)}{(s+w_1)(s+w_2) \dots (s+w_n)}$$

STRICTLY SPEAKING POLES AT $-w_i$
AND ZEROS AT $-z_i$

HOWEVER (FOR REAL AXIS POLES/ZEROS)

OFTEN SAY POLE FREQUENCY AT w_i
OR ZERO FREQUENCY AT z_i

SINCE IF WE ONLY CONSIDER
POLE (OR ZERO) AT w_i

$T(s)$ IS REDUCED BY $\frac{1}{\sqrt{2}}$ AT $T(jw_i)$
(INCREASED)

EX

$$T(s) = \frac{1}{s+1}$$

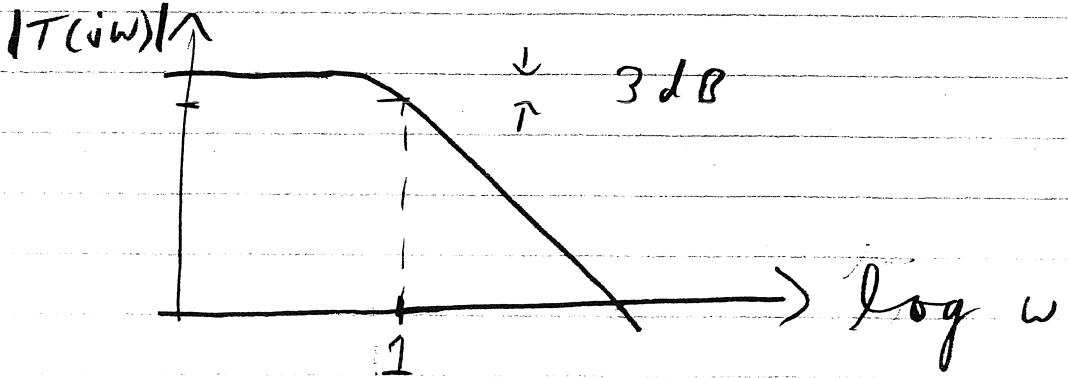
$$T(0) = 1$$

$$T(j\infty) = 0$$

$$T(j1) = \frac{1}{\sqrt{2}}$$

SO FOR $w = 1$ RAD/S

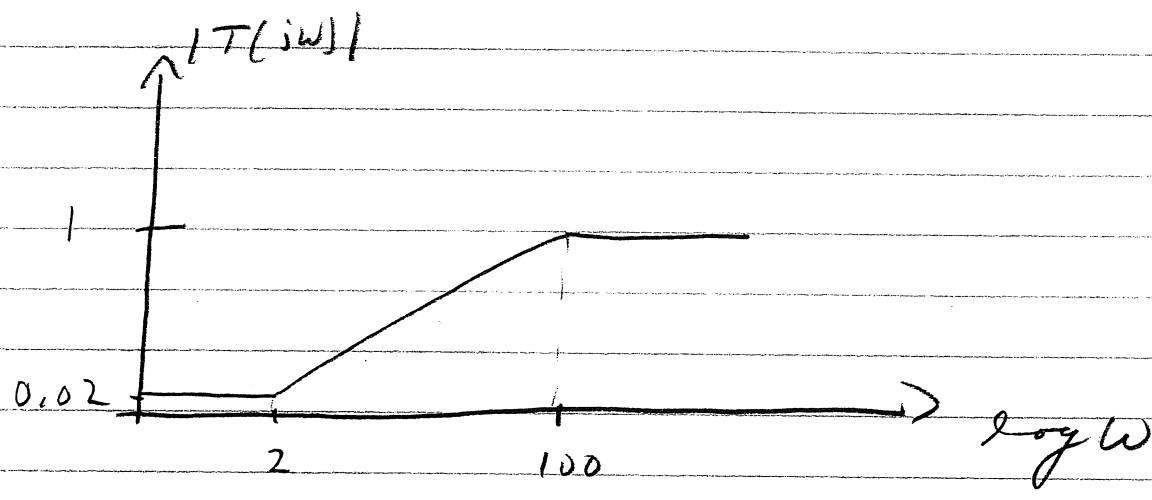
$$|T(j1)| = \frac{1}{\sqrt{2}} T(0) \text{ OR } 3\text{dB DOWN}$$



FR12

EX $T(s) = \frac{s+2}{s+100}$

$T(0) = 0.02$ $T(j\infty) = 1$



$|T(j2)| \approx \sqrt{2} |T(0)|$ 3dB INCREASE

$|T(j100)| \approx \frac{1}{\sqrt{2}} |T(j\infty)|$ 3dB DECREASE

ZERO AT 2 RAD/S

POLE AT 100 RAD/S

ALTERNATE ROOT FORM

FR13

$$T(s) = \left(\frac{a_m}{b_n} \right) \frac{(s+z_1)(s+z_2) \dots (s+z_m)}{(s+w_1)(s+w_2) \dots (s+w_n)}$$

$$\text{HERE } T(j\omega) = \begin{cases} \frac{a_m}{b_n} & \text{IF } m = n \\ 0 & \text{IF } m < n \end{cases}$$

$$T(0) = \left(\frac{a_m}{b_n} \right) \frac{z_1 z_2 \dots z_m}{w_1 w_2 \dots w_n}$$

ALTERNATIVELY $T(s)$ WRITTEN AS

$$T(s) = k_{dc} \frac{(1 + s/z_1)(1 + s/z_2) \dots (1 + s/z_m)}{(1 + s/w_1)(1 + s/w_2) \dots (1 + s/w_n)}$$

$$T(j\omega) = 0 \quad \text{IF } m < n \\ (\text{COMPLICATED IF } m = n)$$

$$T(0) = k_{dc}$$