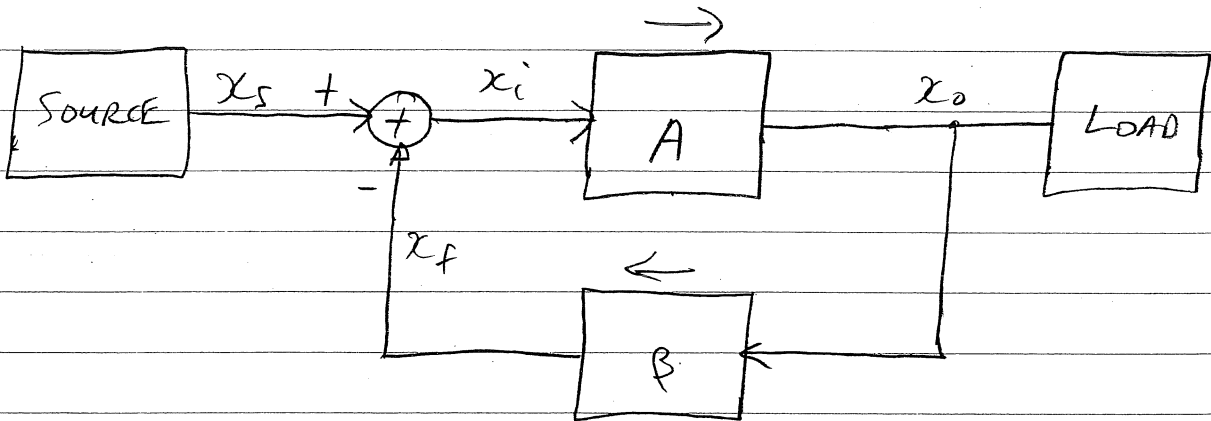


INTRODUCTION TO FEEDBACK

BASIC FEEDBACK STRUCTURE



$x_s, x_f, x_i$  could be VOLTAGES OR CURRENTS

$x_o$  could be VOLTAGE OR CURRENT

A => OPEN LOOP AMPLIFIER

$$x_o = A x_i \quad (1)$$

$\beta$  => FEEDBACK FACTOR  
(USUALLY PASSIVE NETWORK)

$$x_f = \beta x_o \quad (2)$$

$$x_i = x_s - x_f \quad (3)$$

(IF2)

COMBINING ① ② + ③ GIVES

CLOSED-LOOP GAIN,  $A_f$

$$A_f \equiv \frac{x_o}{x_s} = \frac{A}{1 + A\beta} \quad \text{④}$$

WHERE  $A\beta$  IS CALLED THE

LOOP GAIN

DEFINE  $L \equiv A\beta$

(UNITS OF  $L$  DIMENSIONLESS)

$$\text{AS } A \rightarrow \infty \Rightarrow A_f = \frac{1}{\beta}$$

SO CLOSED LOOP IS DETERMINED BY PASSIVE NETWORK (WHICH CAN BE VERY ACCURATE)

ALSO CAN SHOW

$$x_i = \frac{1}{1 + A\beta} x_s$$

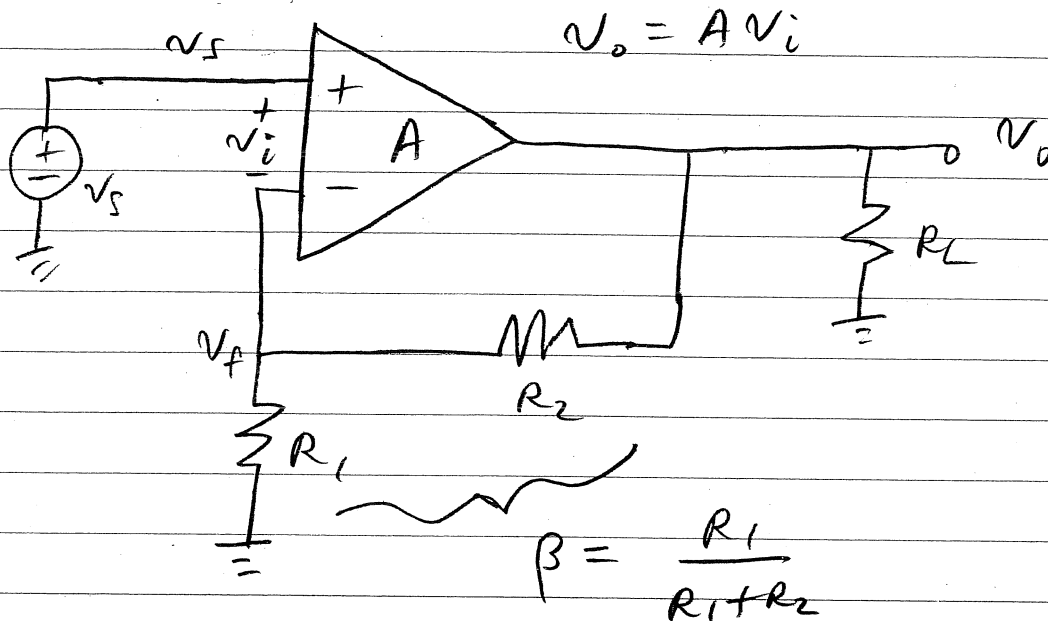
$$\text{SO AS } A \rightarrow \infty \Rightarrow x_i \rightarrow 0$$

IN OTHER WORDS  $x_f \approx x_s$  AS  $A \rightarrow \infty$

THE FEEDBACK SIGNAL,  $x_s$ , TRACKS  $x_o$   
↓ ERROR SIGNAL,  $x_i$  GOES TO ZERO

(IF3)

# NON-INVERTING OPAMP EXAMPLE



$$A_f = \frac{A}{1 + A\beta}$$

$$\text{IF } A\beta \gg 1 \Rightarrow A_f \approx \frac{1}{\beta} = 1 + \frac{R_2}{R_1}$$

EX  $R_2 = 9k$   $R_1 = 1k$

FIND  $A_f$  FOR 2 CASES

1)  $A = 10^4$

2)  $A = 0.8 \times 10^4$

$$1) A_f = \frac{10^4}{1 + (10^4)\left(\frac{1}{10}\right)}$$

$$= 9.99$$

(IF4)

$$2) A_f = \frac{0.8 \times 10^4}{1 + (0.8 \times 10^4)\left(\frac{1}{10}\right)} = 9.9875$$

So A 20% DECREASE IN A

RESULTS IN A 0.025% DECREASE

IN  $A_f$

## USEFUL PROPERTIES OF NEGATIVE FEEDBACK

- GAIN DESENSITIVITY
- BANDWIDTH EXTENSION
- REDUCTION IN NON-LINEAR DISTORTION
- INPUT & OUTPUT IMPEDANCE ENHANCEMENT

### GAIN DESENSITIVITY

USING (4) CAN SHOW (SEE NEXT PAGE)

$$\Delta A_f = \frac{dA}{(1+A\beta)^2}$$

DIVIDE BOTH SIDES BY (4)

$$\frac{\Delta A_f}{A_f} = \frac{1}{(1+A\beta)} \frac{dA}{A}$$

SO A PERCENTAGE CHANGE IN A OF  $K_A^{30}$  RESULTS IN A PERCENTAGE CHANGE OF  $A_f$

OF

$$K_{A_f} = \frac{K_A}{(1+A\beta)}$$

IF5A

(4)  $A_f = \frac{A}{1+A\beta}$  ASSUME  $\beta$  CONSTANT

$$\frac{d(A_f)}{dA} = \frac{d}{dA} \left( \frac{A}{1+A\beta} \right)$$

RECALL (QUOTIENT RULE)  $\frac{d}{dx} \left( \frac{f(x)}{g(x)} \right) = \frac{f'(x)g(x) - f(x)g'(x)}{g^2(x)}$

HERE  $f(A) = A \Rightarrow f'(A) = 1$

$g(A) = 1+A\beta \Rightarrow g'(A) = \beta$

SO  $\frac{dA_f}{dA} = \frac{(1+A\beta) - A\beta}{(1+A\beta)^2} = \frac{1}{(1+A\beta)^2}$

$$dA_f = \frac{dA}{(1+A\beta)^2}$$

(JF6)

EX IF A (CAN) CHANGE BY 10%  
 WHAT SIZE A IS REQUIRED  
 TO KEEP THE CHANGE IN Af LESS  
 THAN 1% IF Af = 20.  
 ALSO FIND β.

---

$$A_f = \frac{A}{1+A\beta} = 20$$

ALSO  $1\% = \frac{10\%}{1+A\beta} \Rightarrow 1+A\beta = 10$

$$A = 20(1+A\beta) = \underline{\underline{200}}$$

$$1+A\beta = 10 \Rightarrow A\beta = 9$$

$$\beta = \frac{9}{A} = \frac{9}{200} = \underline{\underline{0.045}}$$

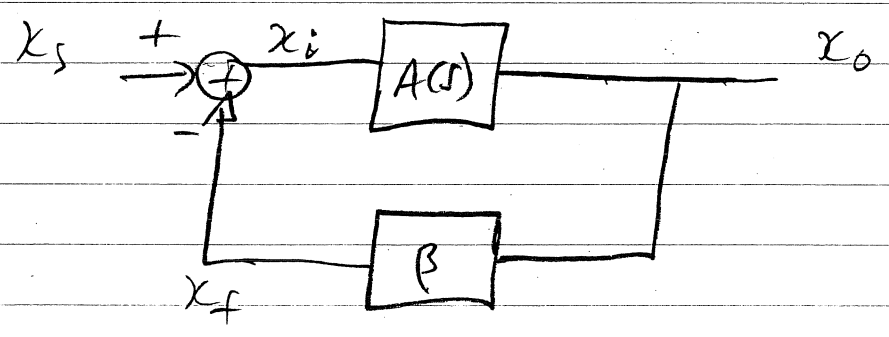
IF  $A \rightarrow \infty \Rightarrow A_f = \frac{1}{\beta} = 22.2 \frac{V}{V}$

BANDWIDTH EXTENSION

AN AMPLIFIER WITH A SINGLE-POLE LOW PASS RESPONSE CAN BE WRITTEN AS

$$A(s) = \frac{A_M}{1 + s/\omega_H} \quad (5)$$

IF THIS AMP IS USED IN FEEDBACK SYSTEM WITH FEEDBACK  $\beta$



$$\frac{x_o}{x_s} = A_f(s) = \frac{A(s)}{1 + A(s)\beta}$$

SUBSTITUTE IN (5)

$$A_f(s) = \frac{A_M / (1 + s/\omega_H)}{1 + s/\omega_H (1 + A_M \beta)}$$



TF8

SO MIDBAND GAIN CHANGED

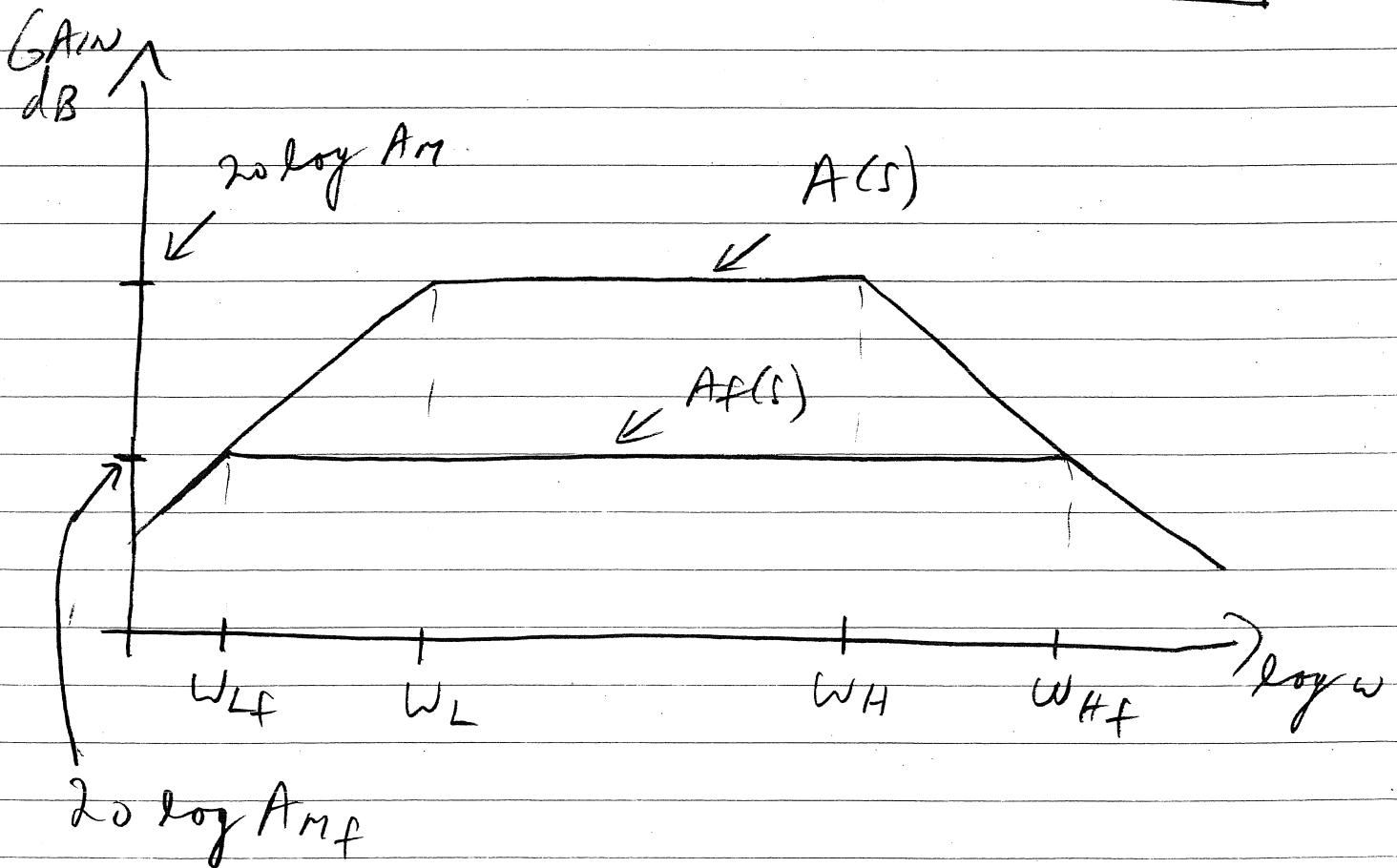
TO  $A_{mf} = \frac{A_m}{(1+A_m\beta)}$

AND 3dB FREQ INCREASED

TO  $\omega_{HF} = \omega_H (1+A_m\beta)$

CAN SHOW SIMILAR RESULT FOR

$\omega_L$  CHANGES TO  $\omega_{Lf} = \frac{\omega_L}{(1+A_m\beta)}$

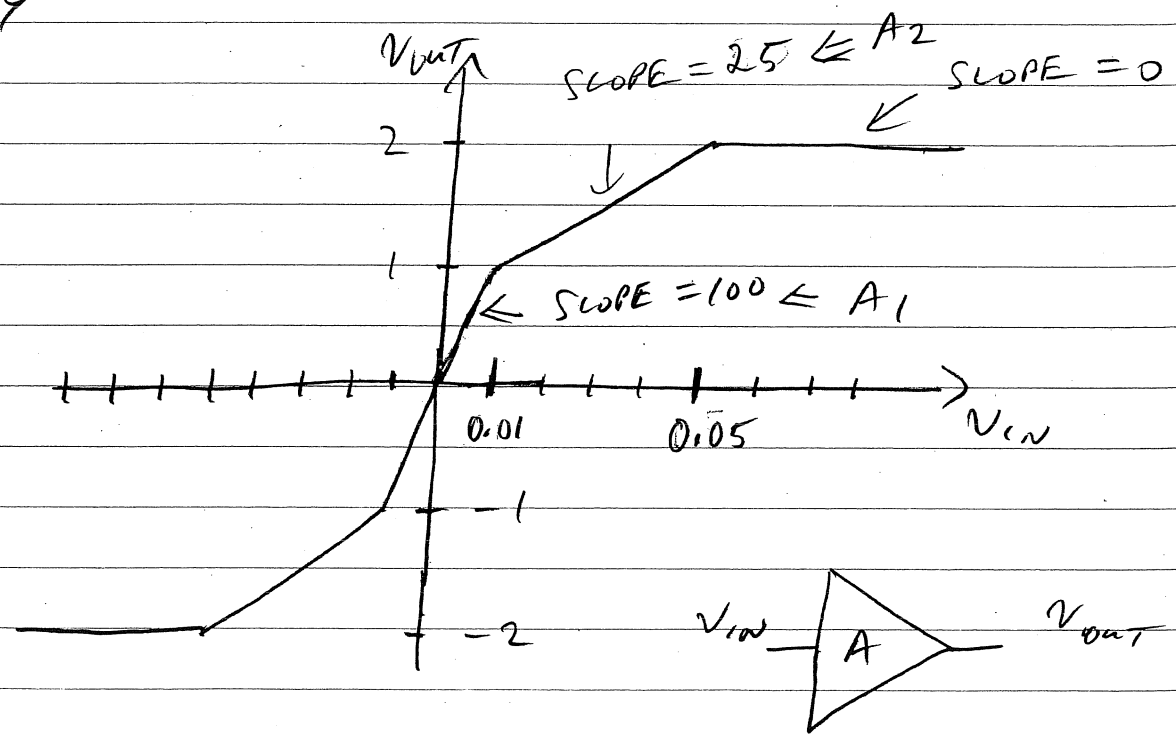


IF9

## REDUCTION IN NON-LINEAR DISTORTION

- NON-LINEAR DISTORTION WILL OCCUR IN AMP IF GAIN CHANGES WITH INPUT LEVEL
- DISTORTION IS WORSE IF GAIN VARIATION IS WORSE

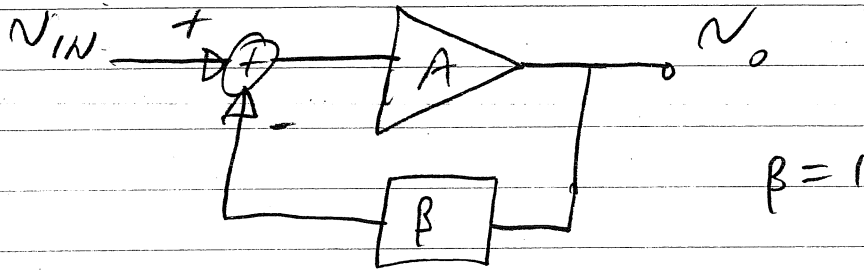
FOR EXAMPLE, CONSIDER AMP GAIN GIVEN BY



LARGE DISTORTION DUE TO GAIN CHANGING FROM 100 TO 25 AND THEN SATURATES WHEN  $|V_o| > 2$  (CLIPPING)

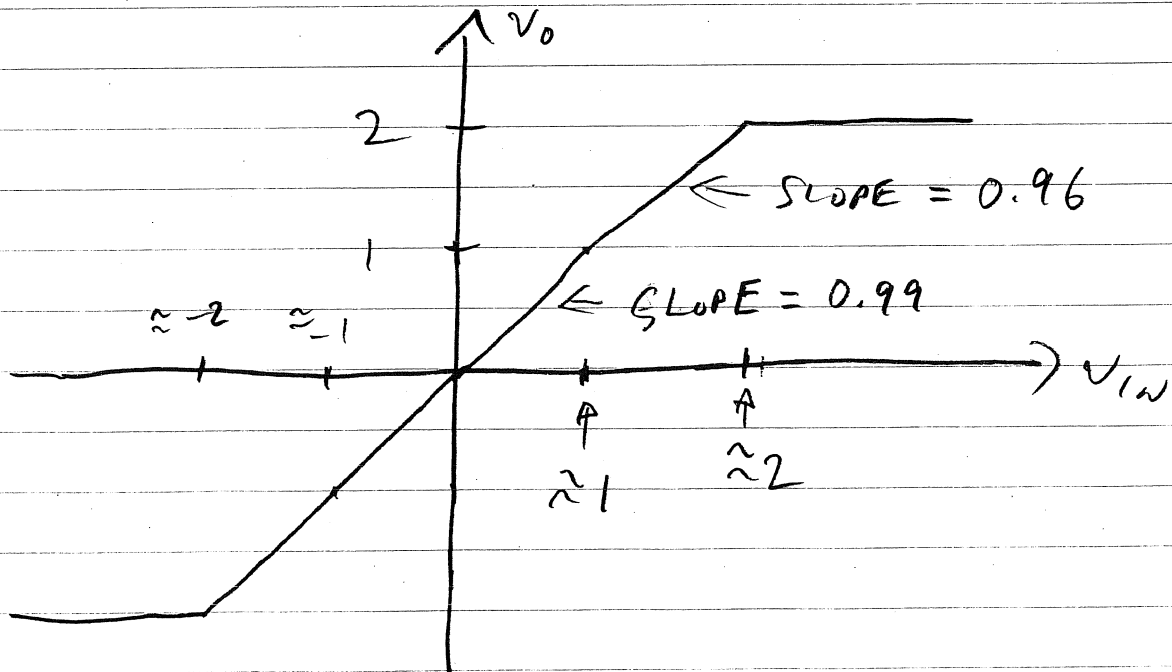
IF10

PWT AMP IN FEEDBACK LOOP  
WITH  $\beta = 1$



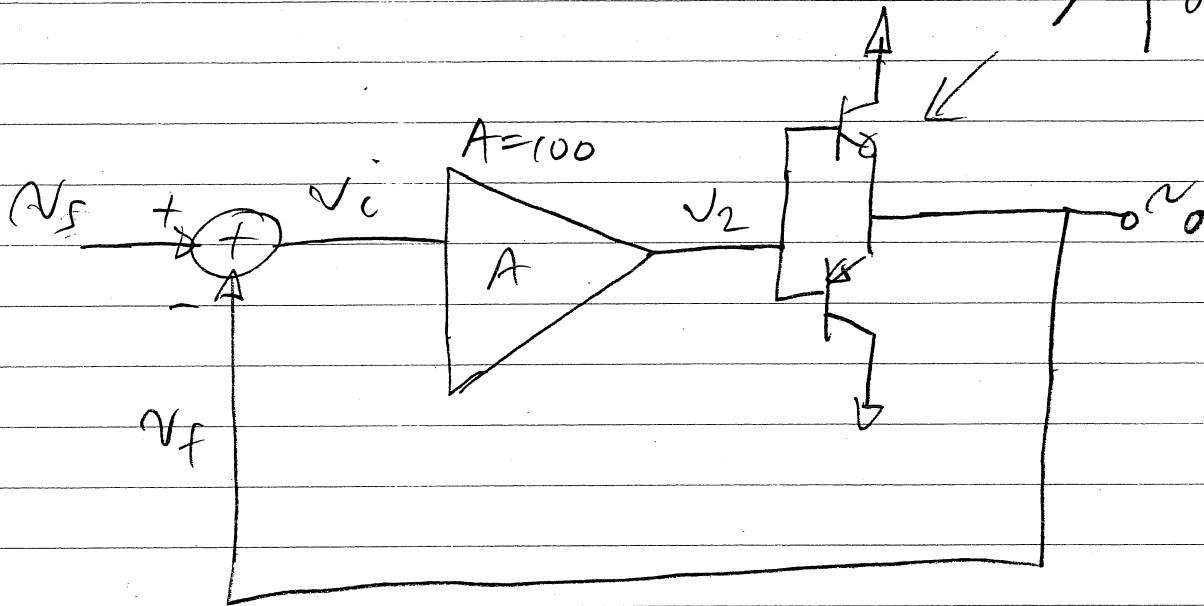
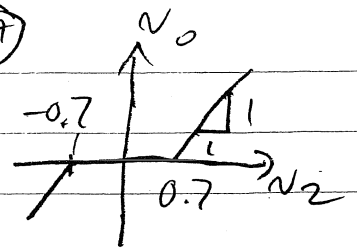
WHEN  $A_1$  GAIN  $A_{f1} = \frac{A_1}{1 + A_1\beta} = \frac{100}{1 + 100}$   
 $= 0.99 \text{ V/V}$

WHEN  $A_2$  GAIN  $A_{f2} = \frac{A_2}{1 + A_2\beta} = \frac{25}{1 + 25}$   
 $= 0.96 \text{ V/V}$



CONSIDER

IF10A



FOR  $v_s = 0 \Rightarrow v_i = 0 \quad v_2 = 0 \quad v_f = 0 \quad \checkmark$

$v_s = 6 \text{ mV} \Rightarrow v_i = 6 \text{ mV} \quad v_2 = 0.6 \quad v_f = 0 \quad \checkmark$

$v_s = 0.7 \text{ mV} \Rightarrow v_i = 0.7 \text{ mV} \quad v_2 = 0.7 \quad v_f = 0 \quad \checkmark$

$v_s = 8 \text{ mV} \Rightarrow v_i = 0.8 \text{ mV} \quad v_2 = 0.8 \Rightarrow v_f = 0.1$   
 $\Rightarrow v_i \neq 0.8 \text{ mV} \quad \times$

WHEN  $v_2 > 0.7 \text{ V} \Rightarrow v_o = v_2 - 0.7$   
(SINCE SLOPE = 1)

SO WHEN  $v_s > 7 \text{ mV}$  WE HAVE

$v_i = v_s - v_f \Rightarrow v_2 = 100 v_i \Rightarrow v_o = v_2 - 0.7 \Rightarrow v_f = v_o$

IF 10B

OR For  $v_s > 7\text{mV}$

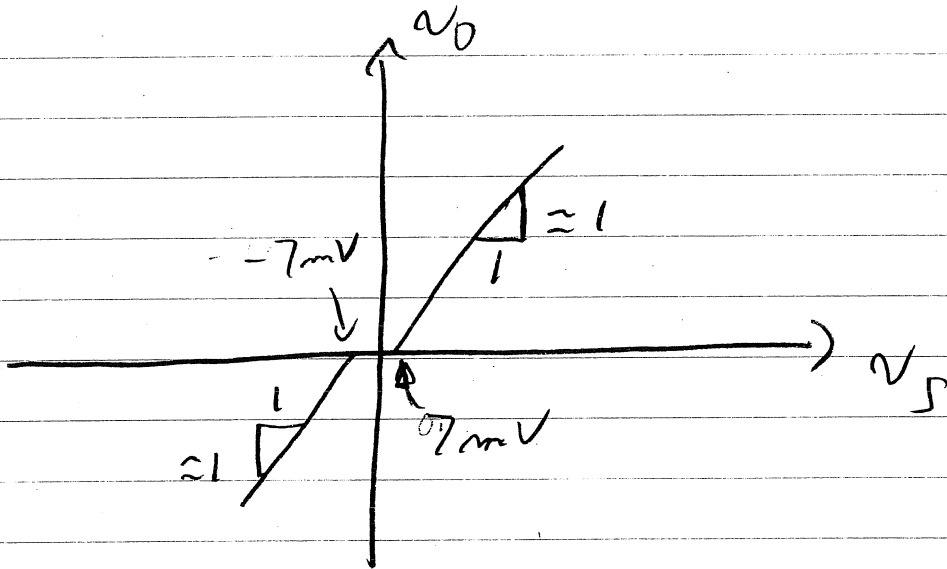
$$(v_s - v_f)100 - 0.7 = v_f$$

EX

$$v_s = 8\text{mV}$$

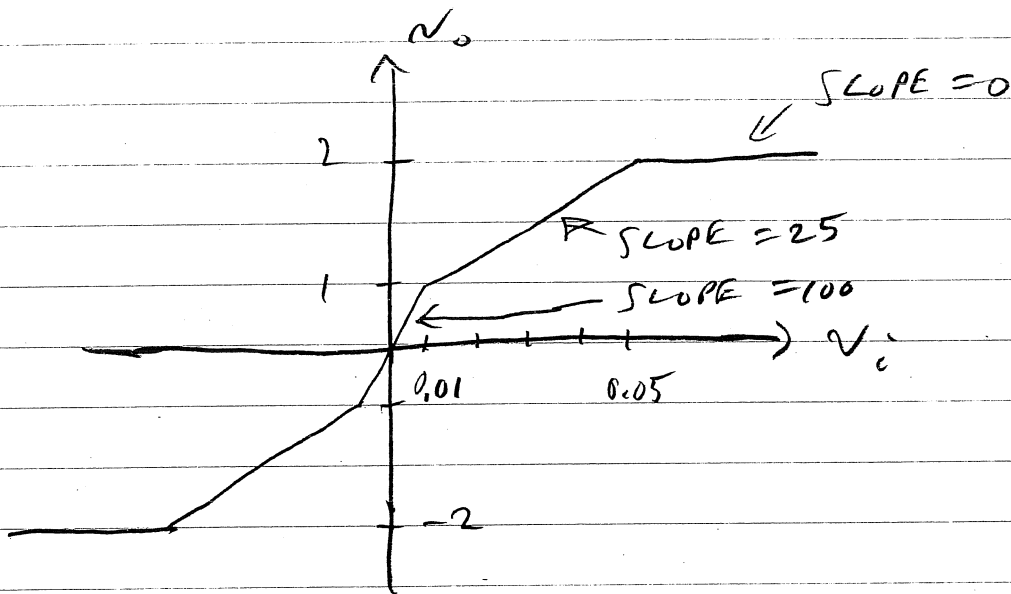
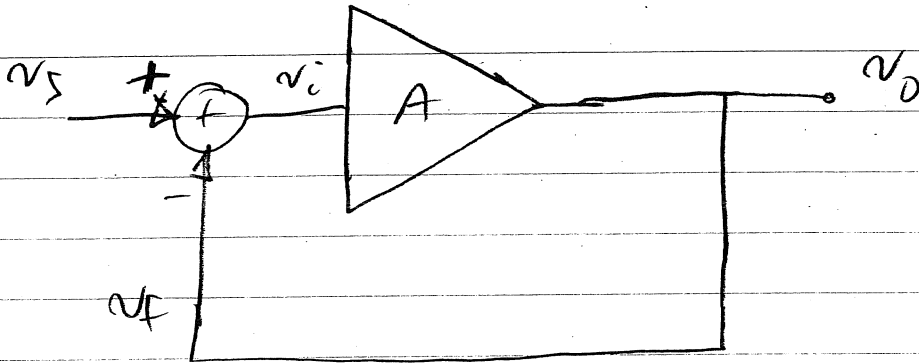
$$(8\text{e-3} - v_f)100 - 0.7 = v_f$$

$$101 v_f = 0.1 \Rightarrow v_f = 0.9901\text{mV}$$



IF10c

CONSIDER



$$v_s = 0 \Rightarrow v_i = 0 \Rightarrow v_o = 0 \Rightarrow v_f = 0 \quad \checkmark$$

$$v_s = 0.01 \Rightarrow v_i = 0.01 \Rightarrow v_o = 1 \Rightarrow v_f = 1 \Rightarrow v_i \neq 0.01 \quad \times$$

NEED EQUATION

$$(v_s - v_f) A = v_o$$

IF 100

FOR  $A = 100$  GAIN

$$(V_S - V_F) 100 = V_F \Rightarrow V_F = \frac{100}{101} V_S$$

$$V_i = V_S - V_F = \frac{101}{101} V_S - \frac{100}{101} V_S = \frac{1}{101} V_S$$

$$V_S = 0.01 \Rightarrow V_F = 0.0099$$

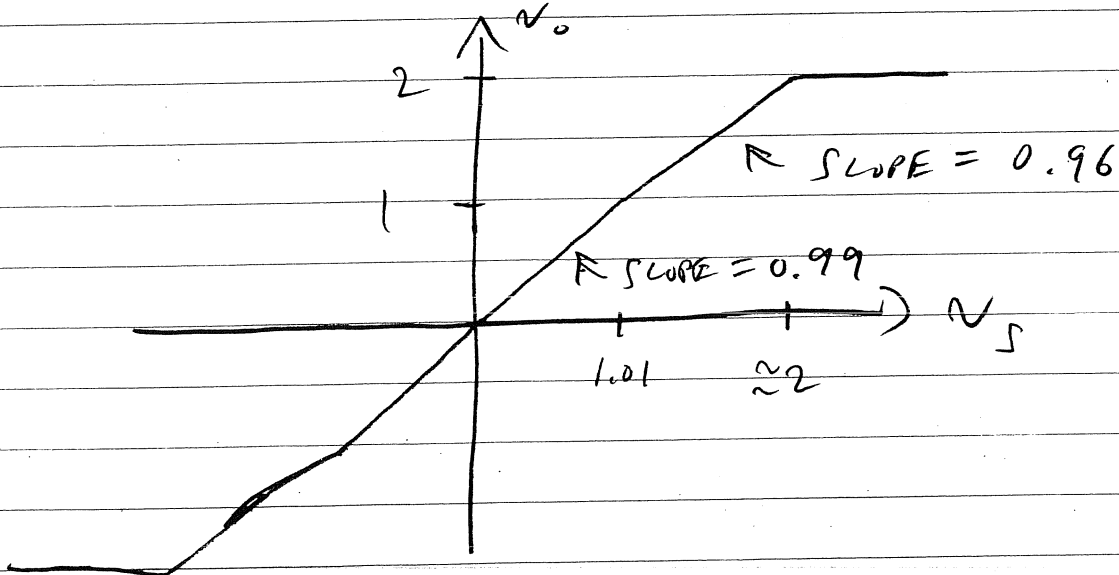
$$V_i = 99.01 \mu V \Rightarrow A = 100 \checkmark$$

(IN GAIN AREA OF  $A = 100$ )

WILL STAY IN GAIN OF  $A = 100$  UNTIL

$$V_i = 0.01 \Rightarrow V_S = 1.01 V$$

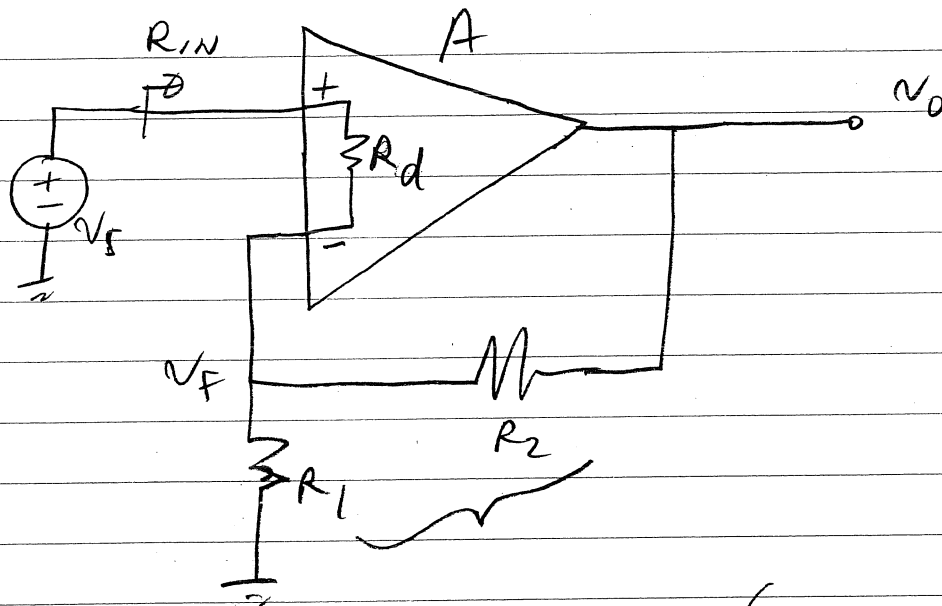
$$\downarrow V_F = 1 V$$



(IF II)

# INPUT/OUTPUT IMPEDANCE ENHANCEMENT

CONSIDER



- WITHOUT FEEDBACK ( $R_2 \rightarrow \infty$   $R_1 = 0$ )

$$R_{IN} = R_d$$

- WITH FEEDBACK & IF  $A\beta \rightarrow \infty$   
THEN  $V_F = V_S$

SO  $R_{IN} \rightarrow \infty$  (SINCE  $i_{R_d} \rightarrow 0$ )

WE WILL SEE THAT GENERALLY FEEDBACK IMPROVES INPUT & OUTPUT IMPEDANCES



EX

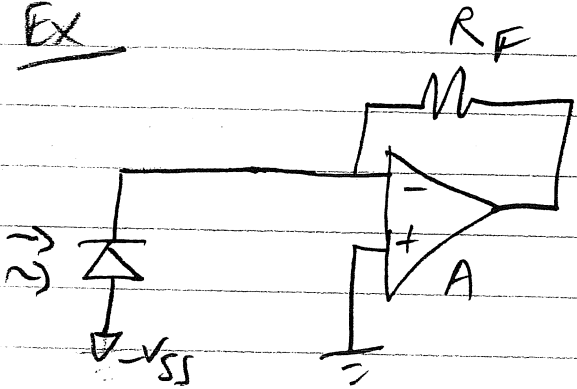


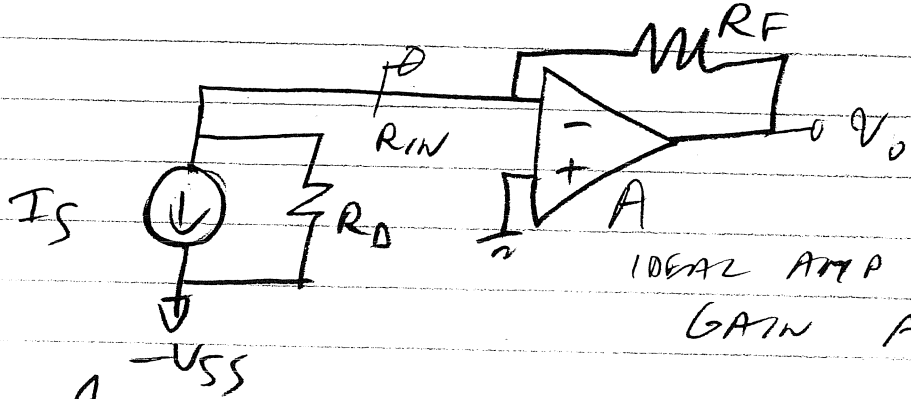
PHOTO DIODE

A PHOTO DIODE RECEIVER

DIODE IS REVERSE BIASED. WHEN LIGHT ILLUMINATES PHOTODIODE REVERSE BIAS CURRENT FLOWS

- LIGHT CREATES ELECTRON/HOLE PAIR IN DEPLETION REGION OF REVERSE BIAS JUNCTION. ELECTRONS FLOW TO POSITIVE JUNCTION WHILE HOLES FLOW TO NEGATIVE JUNCTION.

MODEL PHOTO DIODE AS



IDEAL AMP WITH GAIN A

PHOTO DIODE MODEL

(IF13)

- FROM MILLER EFFECT

$$R_{IN} = \frac{R_F}{1+A}$$

AS  $A \rightarrow \infty$   $R_{IN} \rightarrow 0$

SO ALL  $I_S$  FLOWS INTO  $R_F$   
(NONE INTO  $R_D$ )

$$V_O = I_S R_F \quad (AS \ A \rightarrow \infty)$$

SO  $R_{IN}$  IS REDUCED DUE TO FEEDBACK