Gesture Controller

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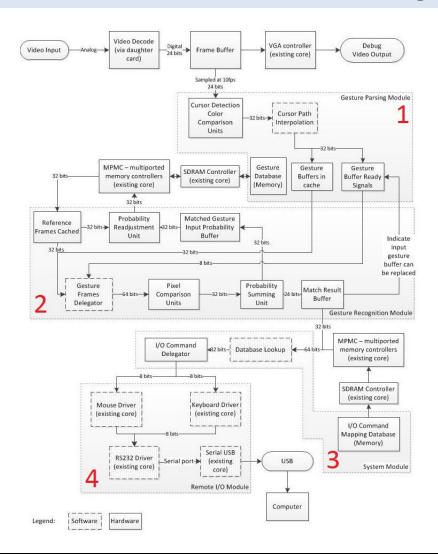




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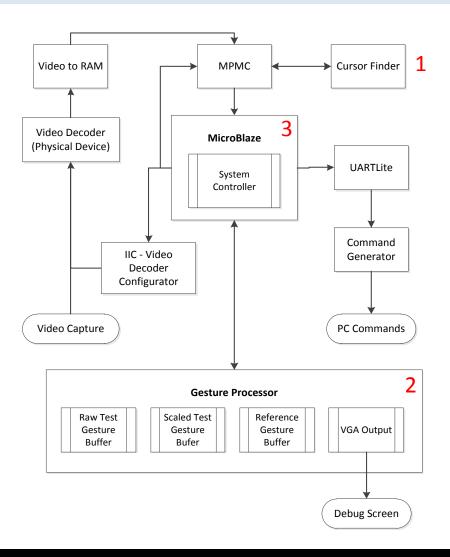
Original Design



Four subsystems:

- 1. Gesture Parsing
- 2. Gesture Recognition
- 3. System Controller
- 4. Remote Communication

Final Design



Three subsystems:

- 1. Cursor Finder
- 2. Gesture Processer
- 3. System Controller
- * Rest is infrastructure

Changes

Subsystem	Original	Final
Gesture Parsing	 Find cursor (shape + colour) Create path (interpolation) Crop and scale gesture Write gesture buffer 	 Find cursor (shape + colour) Pass to system controller via shared memory
Gesture Recognition	 Load references from mem Compare test vs all refs Pass best match to system controller 	 Compare test vs the ref loaded into internal buffer Pass each comparison result to system controller Generate debug video signal
System Controller	 Initialize system Read ready/done signals from modules, coordinate modules 	 Initialize system Generate ref gestures Load ref gestures to buffers Compare recognizer results Send signals to remote PC
Remote Comm.	 Send commands to PC 	Merged into sys controller

Algorithms

- Gesture Parsing
 - Look for pixels with key colour (defined by a range)
- Gesture Recognition
 - Normalize input gesture to reference dimensions
 - Run it through neural network (impl. Gesture Processor)
 - Input: Test gesture pixels
 - Neuron parameters: Reference gestures
 - Output: Match score
- Gesture Creation
 - Run image through Gaussian Filter for encoding probability

Implementation

Existing IP

IP	Source	Function
Video to RAM	Jeffrey Goeders	Buffer raw video to RAM
МРМС	Xilinx	Memory controller
IIC	Xilinx	Low speed communication module, configures video decoder
UartLite	Xilinx	Serial I/O between PC and board
MicroBlaze	Xilinx	General purpose soft processor, used as system controller
BRAM Blocks	Xilinx	Gesture buffers
Hardware Divider	Xilinx	Gesture processor functionality
PLB	Xilinx	System Buses
Paddle Detector*	Past Project, Virtual Pong, 2010	Modified to create cursor finder

Implementation

Our IP

IP, module	Туре	Function
System Controller	Software	 Runs on Microblaze Communicates results from cursor finder to gesture processor Interprets gesture processor's results Signals remote PC
Gesture Processor	Hardware	 Implements neural network as a pipelined pixel processor Contains local gesture buffers Normalizes test gesture Compares against the ref gesture residing in local buffer Generate VGA output displaying local buffers
Cursor Finder*	Hardware	Looks for cursorPasses coordinate to system controller through shared memory
Command Gen.	Software	 Runs on remote PC Monitors serial (USB) port for signals from board Interprets signals and executes task based on signal Displays system feedback messages from board

Implementation

Design Process

- Define interfaces
- Model in software
- Independently developed all modules
- Test in small projects
- Incremental integration

Experiences

- Software easier than hardware
- Use proper source control
- Develop individually, debug as group
- Communicate interfaces in writing, verbal communication is lossy
- Don't need all details to start coding, they change anyways

Questions?